

# Motion Control Systems

V3.0, 4-Quadrant PWM  
with RS232 or CANopen interface

160 mNm  
140 W

## MCS 3274 ... BP4 RS/CO

Values at 22°C and nominal voltage	MCS 3274G	024BP4 RS/CO	
Power supply electronic	$U_P$	12 ... 50	V DC
Power supply motor	$U_{mot}$	0 ... 50	V DC
Nominal voltage for motor	$U_N$	24	V
No-load speed (at $U_N$ )	$n_0$	7 400	min <sup>-1</sup>
Peak torque (S2 operation for max. 1s)	$M_{max.}$	320	mNm
Torque constant	$k_M$	28,4	mNm/A
PWM switching frequency	$f_{PWM}$	100	kHz
Efficiency electronic	$\eta$	95	%
Standby current for electronic (@ $U_P=24V$ )	$I_{el}$	0,06	A
Speed range (up to 36V)		1 ... 11 600	min <sup>-1</sup>
Shaft bearings	ball bearings, preloaded		
Shaft load max.:			
– with shaft diameter	5		mm
– radial at 3 000 min <sup>-1</sup> (5 mm from mounting flange)	50		N
– axial at 3 000 min <sup>-1</sup> (push / pull)	5		N
– axial at standstill (push / pull)	50		N
Shaft play:			
– radial	≤ 0,015		mm
– axial	= 0		mm
Operating temperature range	-40 ... +100		°C
Housing material	aluminium, stainless steel		
Protection class, with option V ring	IP54		
Mass	524		g

### Rated values for continuous operation

Rated torque	$M_N$	160	mNm
Rated current (thermal limit)	$I_N$	5,6	A
Rated speed	$n_N$	6 350	min <sup>-1</sup>

### Interface / range of functions

	... RS	... CO
Configuration from Motion Manager 6.0	RS232	CANopen
Fieldbus	RS232	CANopen
Operating modes	PP, PV, PT, CSP, CSV, CST and homing acc. to IEC 61800-7-201 or IEC 61800-7-301 as well as position-, speed- and torque control via analog setpoint or voltage controller	
Speed range	see motor diagram	
Application programs	Max. 8 application programs (BASIC), one of which is an autostart function	
Additional functions	Touch-probe input, connection of a second incremental encoder, control of a holding brake	
Indicator	LEDs for displaying the operating state Trace as recorder (scope function) or logger	

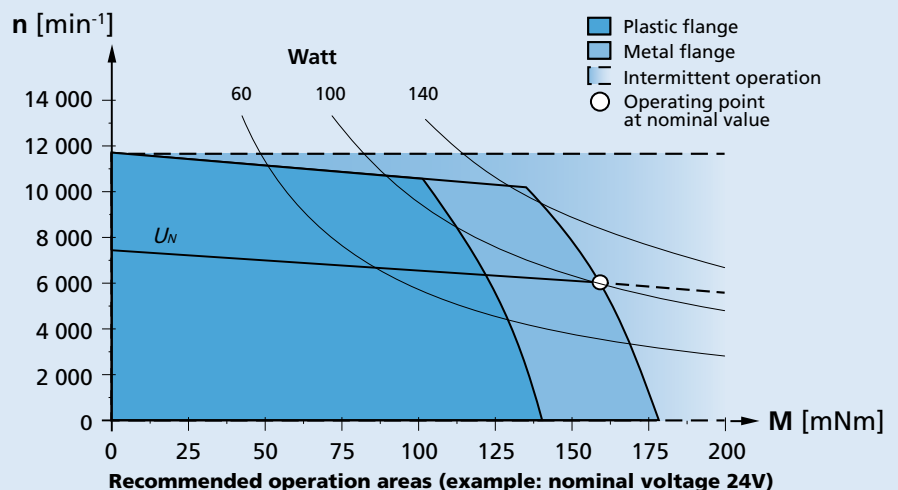
#### Note:

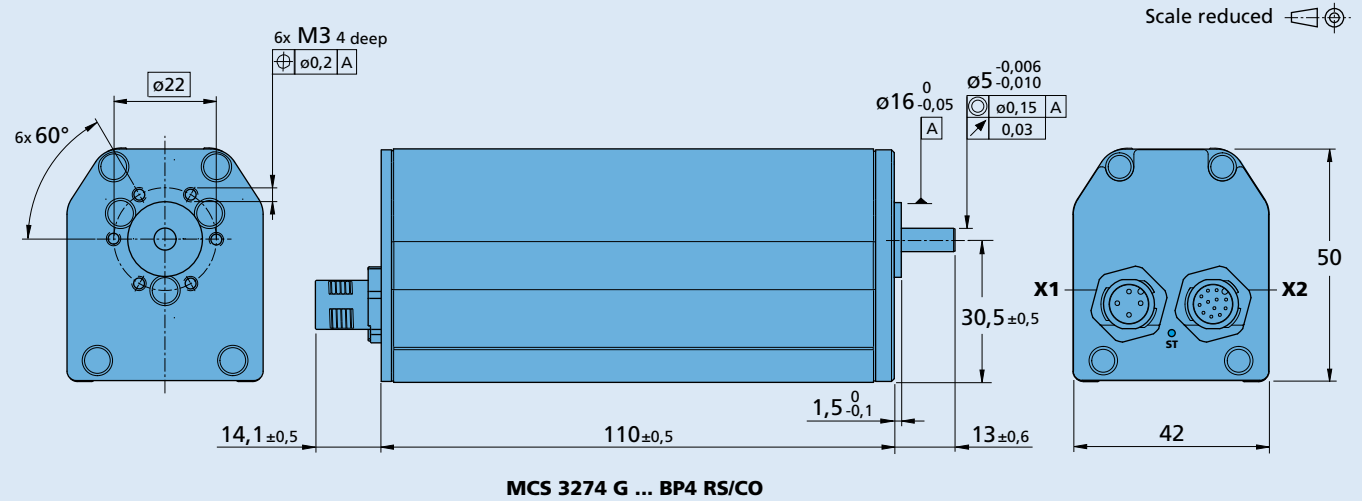
The display shows the range of possible operation points of the drives at a given ambient temperature of 22°C.

The diagram indicates the recommended speed in relation to the available torque at the output shaft.

It includes the assembly on a plastic- as well as on a metal flange (assembly method: IM B 5).

The nominal voltage linear slope describes the maximal achievable operating points at nominal voltage.  
Any points of operation above this linear slope will require a supply voltage  $U_{mot} > U_N$ .



**Dimensional drawing**

**Option, cable and connection information**

 Example product designation: **MCS3274G024BP4RS-5453**

Option	Type	Description	Connection			
			Name	Function	Inputs-outputs	Description
5451	Cable outlet	Radial via base plate	X1	Motor and electronic power supply		
5452	Shaft seal	For use with oil emulsive substances	X2	Inputs / outputs	DigIn1, DigIn2, DigIn3 DigOut1, DigOut2 AnIn1, AnIn2 U <sub>out</sub> / GND	TTL or. PLC level max. 0,7A continuous current $\pm 10\text{V}$ against AGND 5V
5453	Shaft seal	IP54 according to IEC 60529				
5657	Motor flange seal	IP54 according to IEC 60529				

**Note:** For details on the connection assignment, see device manual for the MCS.

**Product combination**

Precision Gearheads / Lead Screws	Encoders	Drive Electronics	Cables / Accessories
32GPT 32/3R 42GPT 32L ... TL 32L ... ML 32L ... SB 32L ... PB		Integrated	To view our large range of accessory parts, please refer to the "Accessories" chapter.